# Scalable Performance Clustering State of the Art and the future

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Presented with MagicPoint

## Definitions

## Cluster: A widely used term meaning

Independent computers
 Combined into a unified system
 Through software and networking

# Cluster Types:

Scalable Performance Cluster
 High Availability (Fail-over) Cluster
 Resource Access Cluster

## What is Beowulf?

#### Beowulf is

Scalable Performance Clusters based on
 Commodity hardware
 Private system network
 Open source software (Linux) infrastructure

## What is Beowulf?

#### Scalable Performance Clusters

□ Improving performance proportionally with added machines

Commodity hardware

□ Mass-market, stand-alone compute nodes

Private system network

□Nodes dedicated to computation

□ Predictable, efficient and a simple security model

Open source software (Linux) infrastructure

□Core software is verifiable

## Why clusters?

#### **Price for Performance**

Obvious initial reason
 Business market pays for engineering
 Efficient distribution and service channels

As-need Scalability

New machines can be automatically added
New, faster machines can replace older machines
Architecture and software remains the same
Investment preserved

Commodity platforms Performance growth rate Better continuity and availability Long-term viability

## Advantages of Commodity Systems

#### **Commodity CPUs**

Always available
Many vendors
Multiple CPU development teams
Rapid improvements

Common environment software □HPC software traditionally "utilitarian" □Software differences a barrier to understanding and use Beowulf Project

The Beowulf Project was started at NASA in 1994
Beowulf was intended to supplement supercomputers
"Beowulf" was an apt project name
Linux continues to be the dominant cluster OS

Scyld Beowulf
Scyld was started in 1998
Redesigned for ease of use and deployment
Scyld Beowulf is the Scyld product
Innovative new generation cluster software
"Scyld" was the father of Beowulf

### Cluster Software

What is important in a cluster software system?

```
Well, what are the problems?
```

Complexity

 System management model
 Installation
 First use learning curve

 Applications to use the system

 Tool availability

 Maintenance

 Maturity and continuity

Understanding the goal helps show the path

Uniform virtual environment Single System Image

Single System Illusion Creating the illusion of a single standard machine No performance impact allowed Changed+simpler is not necessarily simpler How have these problems been addressed in the past?

#### Classic Beowulf

Full OS installation on all nodes
Supports user login on any node
Administration by scripts
Consistency and synchronization tools
Cluster monitoring GUI

## **New-generation Solution**

How the world gotten better?

#### New-generation Beowulf

□ Full OS installation only on "master"

□Compute nodes designed as a computational resource

- □ Single point administration
- □ Single point updates
- □ Single process space view

Centralized monitoring and job control

## Scyld Beowulf

A standard, supported Beowulf cluster operating system Simplifies integration and administration Targeting deployment of complex applications

What it is not: □ Automatic parallelization □ A new language, or □ An integrated development environment.

## Scyld Beowulf Features

#### □"Install once, execute everywhere"

Administration and use is very similar to a single machine
 Dynamically adding compute nodes is fast and automatic
 Scalable to over a thousand compute nodes
 Eliminates software version skew
 Based on Linux
 Open Source software infrastructure

## **Design Philosophy and Goals**

## Administrators

□ Simplicity

□ Minimal new cluster-specific tools

Users

Application users should not need to know they are on a cluster
 Administration should require little new knowledge

Developers

Need to be sophisticated only in application area
Compile-run development cycle, not compile-copy-run
Deployment with a single executable

"Master" front-end Multiple "Slave node" compute machines Booting and configuration controlled from a master

#### Master

□ Full operating system installation

□ All standard tools and utilities available unchanged

□ Supports user login

Provides OS, drivers, libraries and applications Slaves

□Tuned kernel

□No required file system

□No user logins or system services

□No required executables!

### Master-Controlled Cluster System Model



## Why this System Model?

Combines the advantages of A standard user environment Ability to run unchanged applications Specialized compute systems

## Scyld Beowulf Single System Image

Single Installation Single point upgrade □Kernel, drivers, system libraries □User applications, user libraries No version skew Zero-installation scaling □ New nodes take seconds to provision □ Full performance on compute nodes File system semantics selected  $\Box$  At system integration, or □ By administrator Unified process space

## **Operational Details**

Nodes are added dynamically

PXE or Scyld Beoboot booting
Provisioning takes as little as one second
Next started job may use new node
A heartbeat is used to detect missing and failed systems
Immediately removed from scheduling
Eventually running processes reported as crashed
Detection of lost system connection
Compute node default is rebooting after 30 seconds
Configurable behavior

### Subsystems Overview

**Booting and Provisioning Clusters** 

**Unified Process Space** 

**Beowulf Name Services** 

Scheduling

## **Booting and Provisioning**

Functionality not needed with a grid Tightly tied with the architecture and management Some systems mistakenly assume it "just happens" An opportunity and challenge

## **Booting Clusters**

Booting has long been a hot topic
Various boot media
Disk-based and Disk-less models
Safe system software updates problematic
Multiple reporting points for boot problems

## **BeoBoot: Scyld Booting and Provisioning**

#### **Boot requirements**

Reliable network boot
 Dynamic new node addition

□ All run-time components from a controlling system

□Configuration from a central point

Solution

Unchanging boot code

Scyld developed BeoBoot Stage 1
Now ubiquitous PXE network boot

Flow controlled boot server
Kernel and minimal system from a boot server
Configuration and provisioning from a master

### **Beoboot Stage 2: Initial Provisioning**

Beoboot has a minimal initial system
Identifies network devices
Loads network device driver
Contacts server for identity information
Connects to master for configuration

The magic is...

This Space Intentionally Blank

Concept: Configure for specific need

For a compute node:
Master sets time of day
Master mounts file systems
Master starts any application or services

### Compute nodes with Scyld Beowulf

Base system model is "diskless administrative" Only 10-50MB of required cached data Default environment supports most applications Visible /lib/\* libraries /etc/ is mostly empty /etc/passwd and /etc/group are not needed! /etc/mtab exists only so that 'df' works. Name services (hostname, password) are usually bypassed.

Recommended but optional local disks Used for databases and additional caching Optionally mounted and checked on startup

#### Problems:

Starting jobs on a dynamic cluster
 Monitoring and controlling running processes
 Allowing interactive and scheduler-based usage

Opportunity:

Clusters jobs are issued from designated masters
 That master has exactly the required environment
 We already have a POSIX job control model
 Tight communication

## Solution: A Beowulf Cluster Process Space

Create a cluster-wide Unified Process Space Control processes with a local process table entry Forward signals and exit status Precise process creation through migration Remote fork or execute to create processes Implement using checkpoint/restart migration Magic trick: make it fast and efficient

#### Result

All jobs appear to exist on the front-end "master".
Job control and process monitoring work as expected!
Control-Z suspends all jobs, "bg" starts all running
The 'ps' and 'top' programs work unchanged

Start-up □Under 10 msec. to complete a remote job! □10X faster than rsh, 20-30X ssh

No run time performance impact System calls and paging are local Process status update to master is compact and low-rate Only fork(), signals and exit() require a round-trip interaction Compare to transparent process migration of Mosix

### How BProc works

#### BProc is a "Directed Process Migration" Mechanism BProc has architectural elements of

- □Remote Fork
- □ Process migration
- □Checkpoint / restart
- Design details
- □VMA dump and restart -- essentially "checkpoint" to a socket/stream
- $\Box$  In general, files and sockets are closed
- ostdin, stdout, and stderr may remain connected
- □ Process environment info (process ID) appears unchanged
- □ Preserves POSIX process family semantics
- $\Box$  Signals (SIG\*) are forwarded both ways.
- $\Box$  Slave updates state to master.
- □ Resource usage on exit

### How can this be Fast?

□ Cached libraries ("VMA regions") □ Copy on changed pages in known VMA regions □ Copy unknown VMA regions

Improvements
Better dynamic caching of objects
Caching selection of RAM (default) or local disk
Pluggable transport selection e.g. TCP or Myrinet
Detach process and re-master node

### Name Service / Directory Service

"Name Service" and "Directory Service" mean the same thing.

A directory service Description A directory service A directory service A directory service Description A directory service Descri

Specific Examples User names • Password and user information Host names • IP addresses and Ethernet MAC addresses • Network groups • A list of similar hosts

### **Benefits of Cluster Nameservices**

Why are cluster nameservices important?

Simplicity
Eliminates per-node configuration files
Automates scaling and updates
Performance
Avoid the serialization of network name lookups.
Avoid communicating with a busy server
Avoid failures from server overload
Avoid the latency of consulting large databases

Why can we do a better job?

Clusters have a single set of users User credentials available at job initiation point New nodes will have predictable names Cluster nodes are granted similar access permissions

## Solution: BeoNSS, Beowulf Name Services

#### BeoNSS is a mechanism that

Caches,Computes orAvoids name lookup

#### Hostnames

Cluster hostnames have the form .<N> Syntax does not conflict Compare with DNS and local hostnames Special names for "self" and "master" Current machine is ".-2" or "self". Master is known as ".-1" OAliases of "master" and "master0".

Cluster nodes start at ".0" □ Zero based for flexibility □ Do not assign ".0" for 1-based naming □ Extend to maximum node e.g. ".31" □ Maximum resolvable number defined.
Names are reported as password table entry 'pwent'

Processes are moved with their user information BeoNSS reports only the current user and root Cluster jobs do not need to know other users Much faster than scanning large lists

#### Other name services

#### Netgroups to automate file server export security Services and Protocols databases

All common, fixed values
 Frequency of use analysis to select and sort entries

#### Scheduling on Grids vs. Clusters

Similar words and concepts are used Opportunities and thus architecture differ Clusters support interactive and administrative use Scheduling: A combination of concepts about running jobs

Queuing: Delaying jobs until resources are available Backfill: Reordering queue for better utilization Mapping: Assigning processes of a job to nodes Environment Configuration: Making files, etc. available Job Initiation: Creating processes on specified nodes Job Control: Stopping, resuming and killing processes Reporting: Tracking resource usage and exit status Environment Clean-up: Undoing configuration

# Scyld Beowulf Scheduling Support

Queuing: BBQ, or external scheduler Backfill: Only with external scheduler Mapping: Beomap, NPR, or external scheduler Environment Configuration: Ad hoc, responsibility of job Job Initiation: BProc Job Control: BProc Reporting: BProc Environment Clean-up: Ad hoc Scyld supports external schedulers,

Differences between Scyld and External Schedulers

Scyld programs call library functions for a map Extensible by dynamic loading libraries into the application

External Schedulers provide a daemon that schedules jobs Extensible by loading dynamic libraries into the daemon

### Scyld Scheduler Interface

Scyld provides centralized scheduler support

#### Use Beostat library

node capability: processor count, speed, memory
status: load average, free memory
Use BProc library for node state
Node state is up
Permission for user execution
Option to force scheduler-only job submissions
Set node group ownership to scheduler
Set execute permission only for group

### BeoMap, the Scyld Mapping System

Beomap is a layered job mapping system Programs call beomap functions Scripts call 'beomap' program Thin wrapper for mapping function NODE=beomap --no-local --np 1 Mapping interacts with node status Node state -- only use 'up' nodes Node information -- need free memory

## **BeoMap Implementation Layer**

The BeoMap system allows "pluggable" schedulers

Looks for system- or user-provided dynamic library
Library function is passed a key (program name)
Default scheduler is good for most uses
Looks for least-loaded nodes
Prefers grouping processes on SMP nodes
Sorts node list by node number
Extended schedulers
Have access to program name, BeoStat library and BProc state

# ВеоМар

BeoMap: a better approach
Other schedulers are daemon-based
Loading dynamic libraries is more efficient and flexible
Users and administrators may install customized rules
Complex network topologies may be handled
Why is this possible in Scyld?
Kernel-enforced node ownership mechanism
Invalid mappings simply fail.
Daemon-based schedulers must be closed systems
May not execute arbitrary user code
Must use only their internal statistics and job monitoring

# Using Scyld Beowulf Cluster

# **Application Server Cluster**

Compute nodes used as server nodes Inverts traditional cluster network Server nodes connect to master and Internet Master is firewalled by server nodes

# **Application Server Security**

Highly Secure Server Nodes

No network services to exploit
No OS password information
No local executables
Applications "locked" to not migrate from node

#### Example Script

Script Run on master at start Uses standard \*NIX process concepts

```
    while true; do
    NODE='beomap --no-local --np 1'
    bpsh $NODE appserver
    logger -t appserver Exited with status $?
    done
```

### Using Beowulf Process Space (BProc) Calls

Cluster applications can be very simple.

Basic call is bproc\_move(), bproc\_rfork()

Remote move or fork semantics
Takes a numeric destination node ID.
Available node ID may be found from the NPR or beomap library
Resulting processes controlled with \*NIX interface

See 'modprobe' for a great example Reads dependency file from the master Reads kernel symbols from the slave Reads driver module from the master Loads module into slave kernel

#### Pragmatic Issues

Scyld is a complete supported OS distribution Ships as installation/upgrade CDs Provides isolation from unexpected "upgrade" changes Allows delivering a real cluster OS Automated installation part of consistent deploys Avoid system changes with re-install Don't confuse installation time with learning!

## Implications of Single System Image

# Single System Image and ad hoc installations are fundamentally at odds

One kernel over cluster
 Consider a Filesystem or NIC driver update
 One set of utilities over the cluster
 Node specialization not a conflict with this principle

Selecting an optimized kernel is not automatic Per-machine library and kernel optimizations problematic Breaks singles point, single file updates Breaks application portability and repeatability

# **Node Specialization**

Specialization allowed by

Specific machine (MAC address)
Position in cluster (node number)
Hardware resources
Heterogeneity support
Range of support hardware is a common question
Instruction set must be the same

Cannot run the application otherwise
Installed hardware detection is automatic
Drivers installed based on e.g. PCI ID

#### **Operation Issues**

Dynamically, automatically scalable New nodes assigned a permanent node number Based on MAC address Manual intervention to renumber New nodes take only seconds to provision 750 msec for base system Disk detection and file system mounts extra All system tools should be "hard" and single layered

Don't rely on interpreters: "Perl v5.6.1.33 only" Reserve interpreters for end site use Provide language bindings for system interfaces Single layer implementation Human-oriented text configuration files Trace problems back to the original configuration Generated configuration files are a potential disaster Libraries, shell, command line and GUI interfaces GUIs Provide an officient monitoring interface

Provide an efficient monitoring interface

□ Example: Keep vital state mappable shared memory

#### Future

Even better boot and failure analysis system □ PXE-based CPU and NIC detection □Complete boot state (failure) reporting Environment and kernel fault reporting Multiple master architectures □ Different structures are possible □ Automatic detection and configuration needed Integrated process mirroring □ Extension to existing migration □ Opportunity with InfiniBand and other RDMA □ Client pull may increases scalability □ Reliability trade-off Complete virtual environment creation and mirroring □Too inefficient today □ Extend process migration to environment migration

And now the commercial message

Training available on-site or scheduled Northrop Grumman hosts training in D.C. area

Scyld Beowulf is available on GSA and SEWP Integrated clusters, integration services, professional services

Penguin Computing provides standard clusters Most common commercial cluster deployments: AMD Operton w/ gigabit Ethernet or Infiniband Intel Xeon on racks or blades